

Experimental approaches to understanding the evolution of flight surfaces in dinosaurs: Kurochkin & Bogdanovich (2008) revisited

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Birds: 10,000 spp.

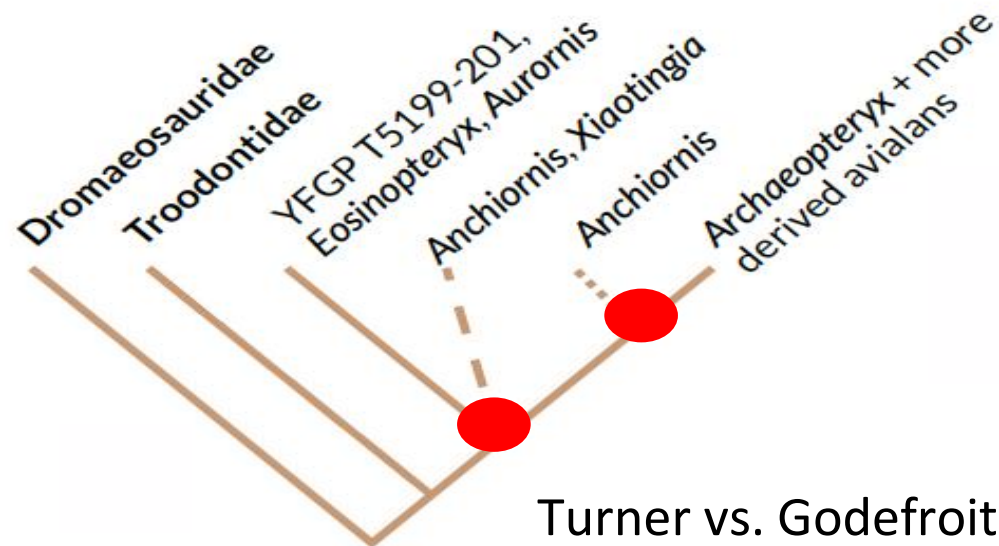
Descendants of a large and ancient radiation



Birds: 10,000 spp.

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To understand early wing evolution, paravian theropods are key



Turner vs. Godefroit

4/5 winged taxa,
Microraptor/Anchiornis

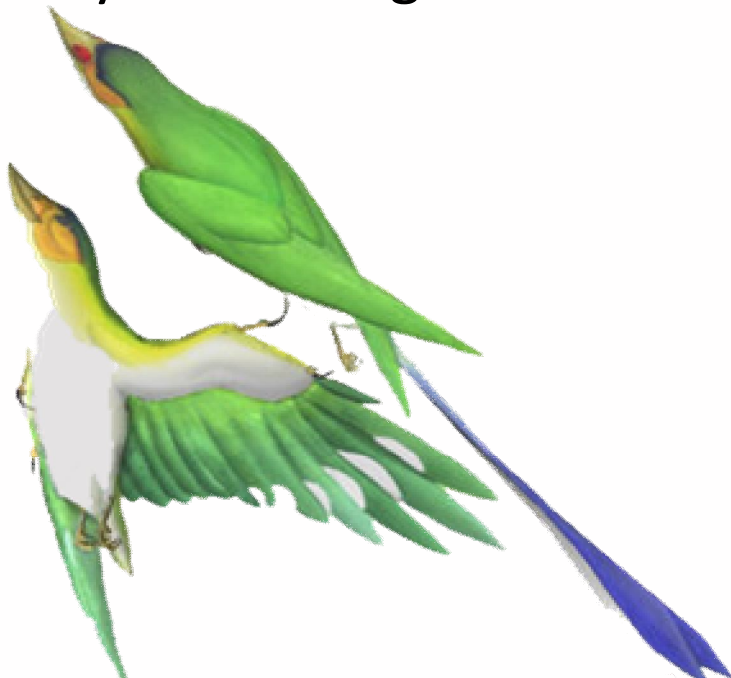
Context -

Pennycuik (2008), 3 basic achievements required of birds:

(1) Ability to control spatial orientation while being free to move and rotate in 3D, without contact with the ground;

(2) Development of a shape that gives a sufficiently high L/D embodied in a structure that is able to withstand loads of flight;

(3) Development of a source of power that can be used to overcome aerodynamic drag.



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Outline – paravian wings:

- experimental results on *Microraptor**;
- early wing configuration from fossils.

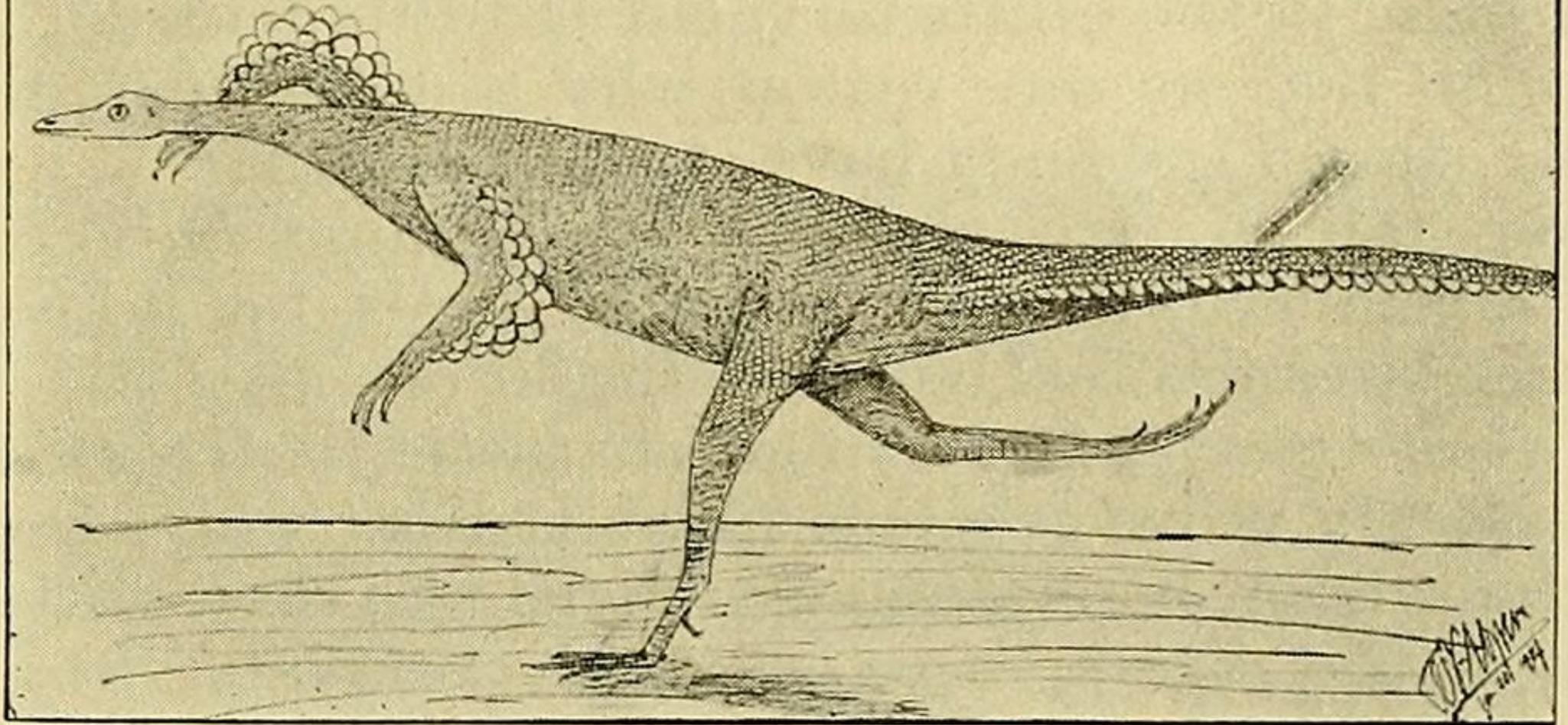
*Dyke et al. *Nature Comms.* (2013)

The BIG question really is Pennycuik's (2) and (3):

Proavis

F Nopsca 1907

How did bird wings evolve?



This is related to an even more famous debate: 'ground up' or 'trees down'?

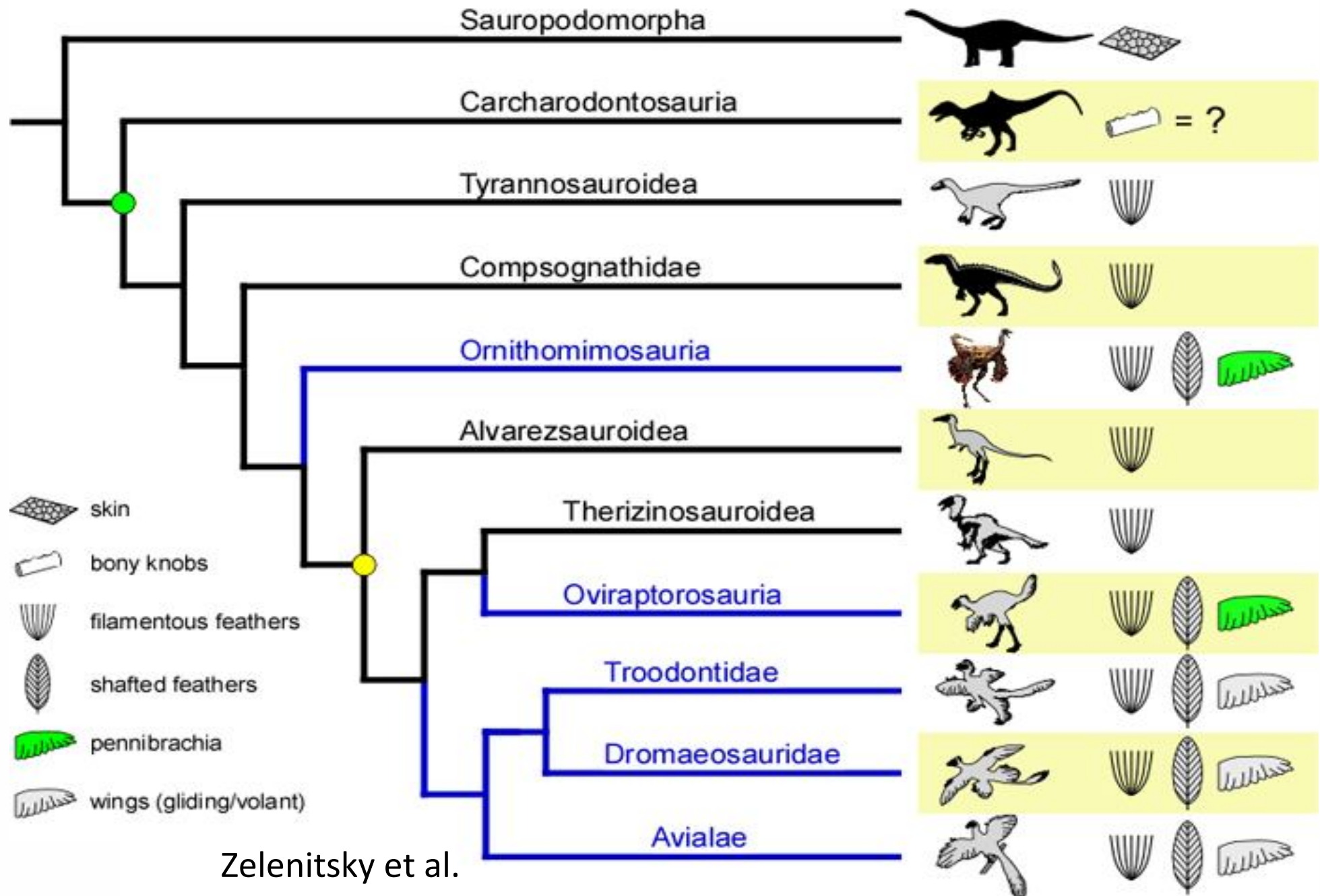
Reconstructing the flight ability of fossil animals



FIG. 7. TETRAPTERYX STAGE IN THE ANCESTRY OF BIRDS

The drawing is based on characters present in Archaeopteryx, and in the young of living birds

Context - what we know about feather evolution in dinosaurs?



Aerodynamic performance of the feathered dinosaur *Microraptor*



- Microraptor* had 4-5 wings
- Beebe (1914)
- Nature of flight and wing configuration has been much debated
- Stem to the origin of birds (cf. *Archaeopteryx*)



FIG. 7. TETRAPTERYX STAGE IN THE ANCESTRY OF BIRDS
The drawing is based on characters present in *Archaeopteryx*, and in the young of living birds

Modelling *Microraptor*



- accurate geometries, joint morphologies and feathering (pigeons and ducks)
- previous reconstructions based on flat models, or speculation based (more or less) on fossils

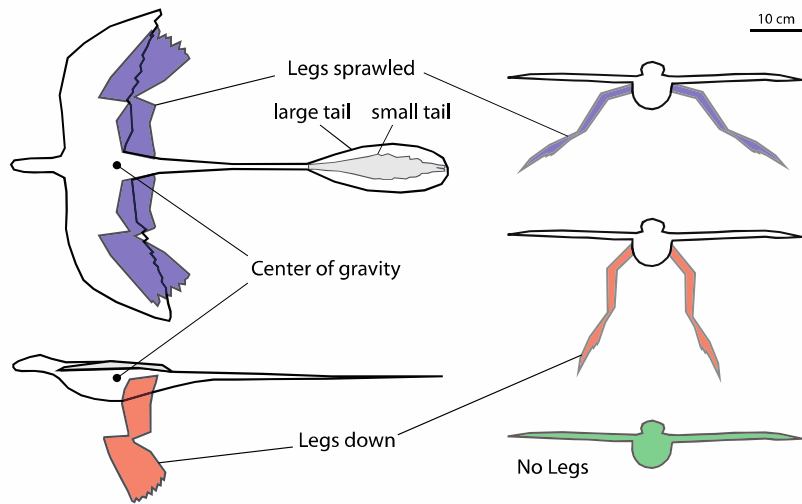
Modelling *Microraptor*



-No consensus on likely wing configurations (thus degree of stability and glide performance) has been attained, reflected in a factor of six range of predicted lift-to-drag (L/D) ratios.

-L/D is one fundamental measure of flight performance determining minimum glide angle and thus maximum flight range under steady conditions.

Experimental protocols



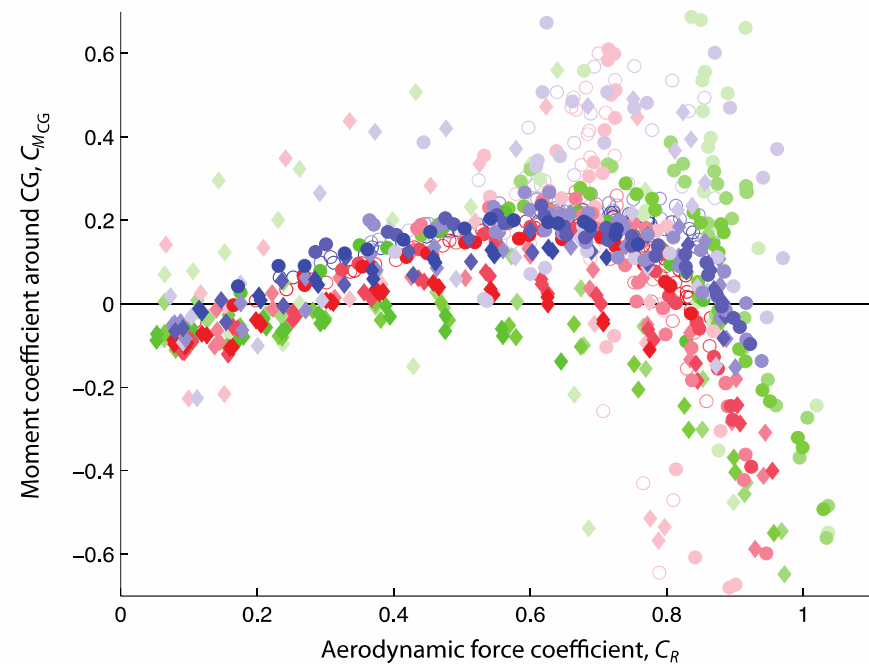
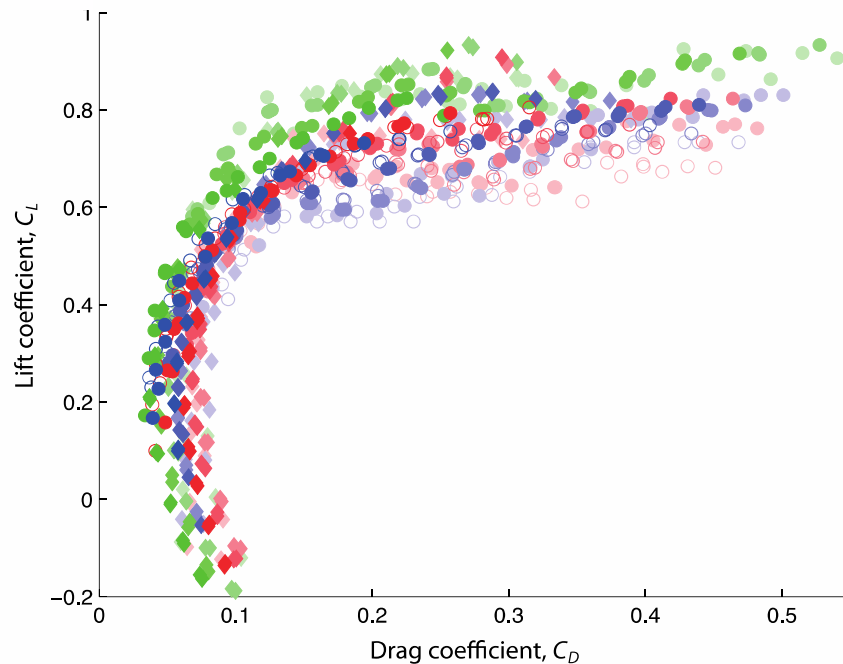
| 5 m/s | 10 m/s | 15 m/s | 20 m/s | |
|-------|--------|--------|--------|---|
| ◆ | ◆ | ◆ | ◆ | Legs sprawled, main wing low angle, large tail |
| ● | ● | ● | ● | Legs sprawled, main wing high angle, large tail |
| ○ | ○ | ○ | ○ | Legs sprawled, main wing high angle, small tail |
| ◆ | ◆ | ◆ | ◆ | Legs down, main wing low angle, large tail |
| ● | ● | ● | ● | Legs down, main wing high angle, large tail |
| ○ | ○ | ○ | ○ | Legs down, main wing high angle, small tail |
| ◆ | ◆ | ◆ | ◆ | No legs, main wing low angle, large tail |
| ● | ● | ● | ● | No legs, main wing high angle, large tail |

- range of flight velocities and whole animal angles of attack
- 8 different configurations (all previously proposed that are anatomically viable)
- 3 different leg configurations, 3 main wing angles of incidence relative to the body and 3 different tail sizes
- 4 different flight velocities (covering the range consistent with those experienced by living gliding and flapping animals): 5 m/sec to 20 m/sec

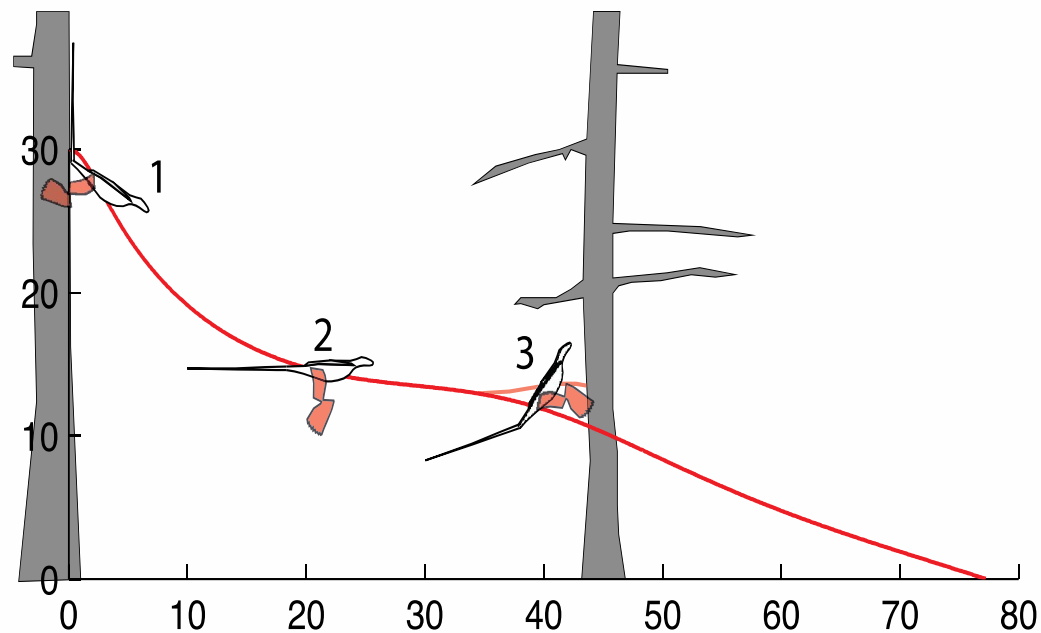


Some experimental results

- L/D glide polars for the model *Microraptor* in different configurations and pitching moment coefficient against aerodynamic force
- Data show that configurations with a low angle between the main wings and tail had increased glide efficiency at high values of C_r , while altering the size of *Microraptor's* tail made no significant difference to its aerodynamic characteristics



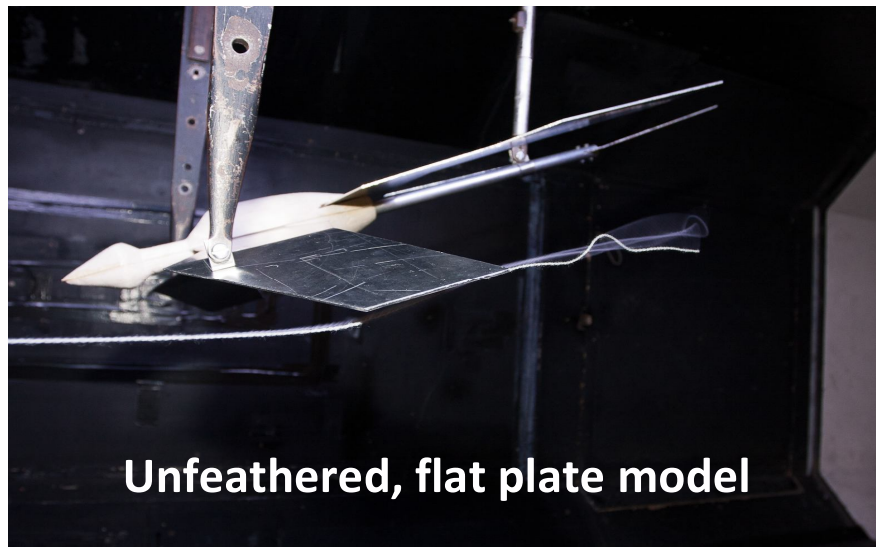
Predictions



- Glide path simulation shows that *Microraptor* would have performed best in shallow glide with its legs held down
- Best performing of all possible configurations is an **anatomically impossible** *Microraptor* without legs (= evolution of hindlimb feathering) (**next best is with legs down**)
- Achieving a high CL was most important for *Microraptor*'s flight (arguments about wing configuration and leg position less critical) (**so wing area is key**)
- Differences in gliding leg position only lead to very small differences in performance, a legs down configuration is most likely.

The flight of *Microraptor*

- The most important factor for this theropod was attaining sufficient wing area (**for which derived feathers are unnecessary**); theoretically, all *Microraptor* needed to glide at high CL was an impervious surface
- Comparing feathered and unfeathered models (flat plate experiments) demonstrates that the well-developed asymmetric feathers of *Microraptor* were not necessary to support its high CL (close to stall) flight style
- Congruent with, and builds on, fossil evidence that shows theropod filamentous integument and symmetric wing feathers first evolved for behaviours other than lift generation



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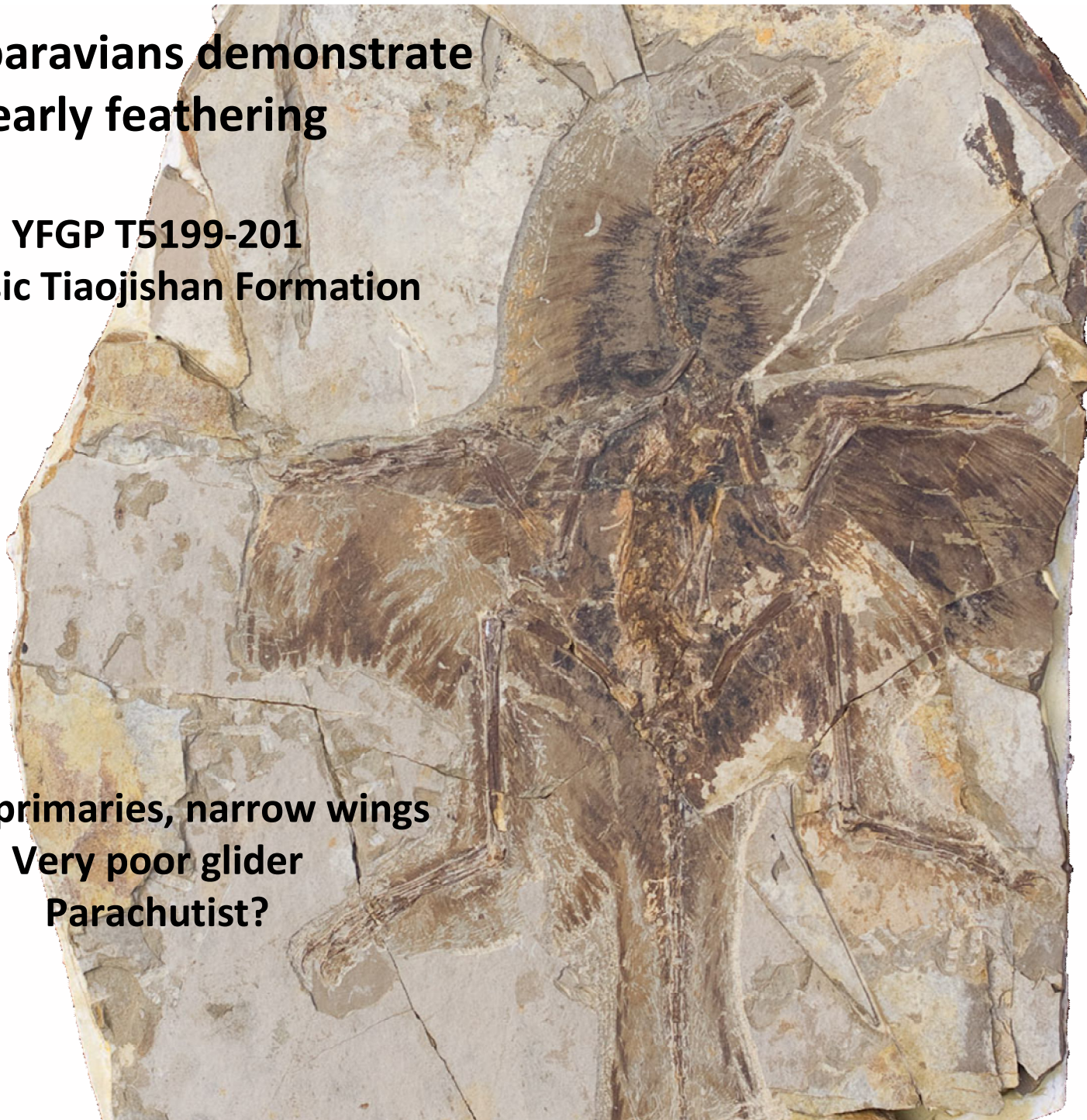
AMNH diorama, photo Roderick Mickens

**Other paravians demonstrate
early feathering**

YFGP T5199-201

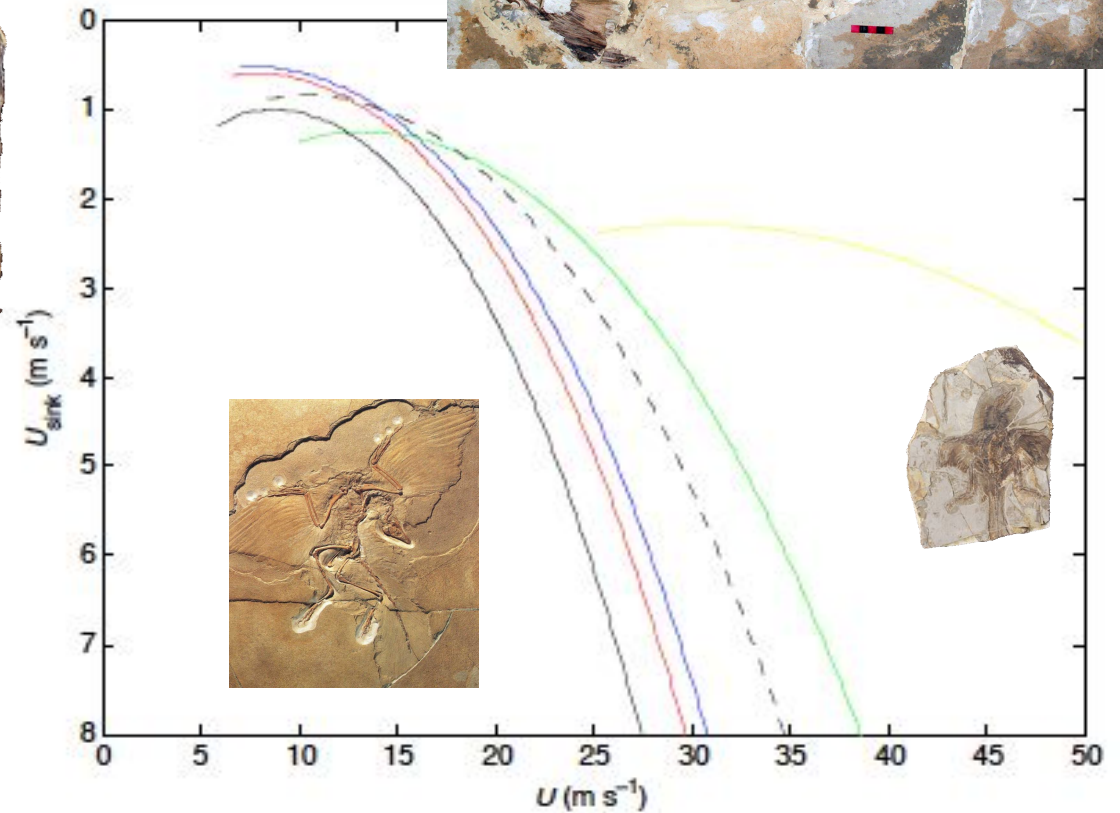
Jurassic Tiaojishan Formation

**Short primaries, narrow wings
Very poor glider
Parachutist?**



5cm

Early results: Sink speed versus forward velocity



Increasing wing-area (a broad wing) increases the minimum sink speed (reduces glide length): you can glide slower

YFGP-T5199-201 also reveals information on feathering



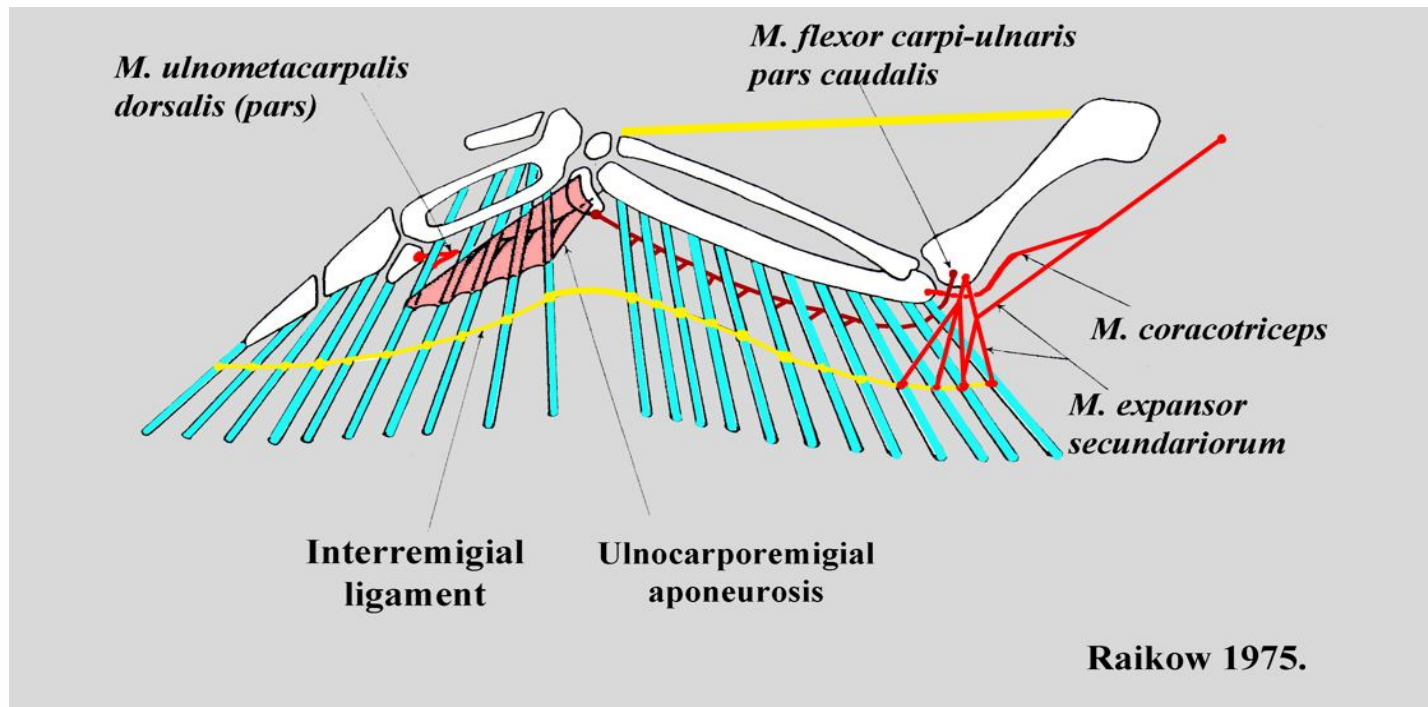


Confuciusornis:
a glider?



© 2008 Greg Cope

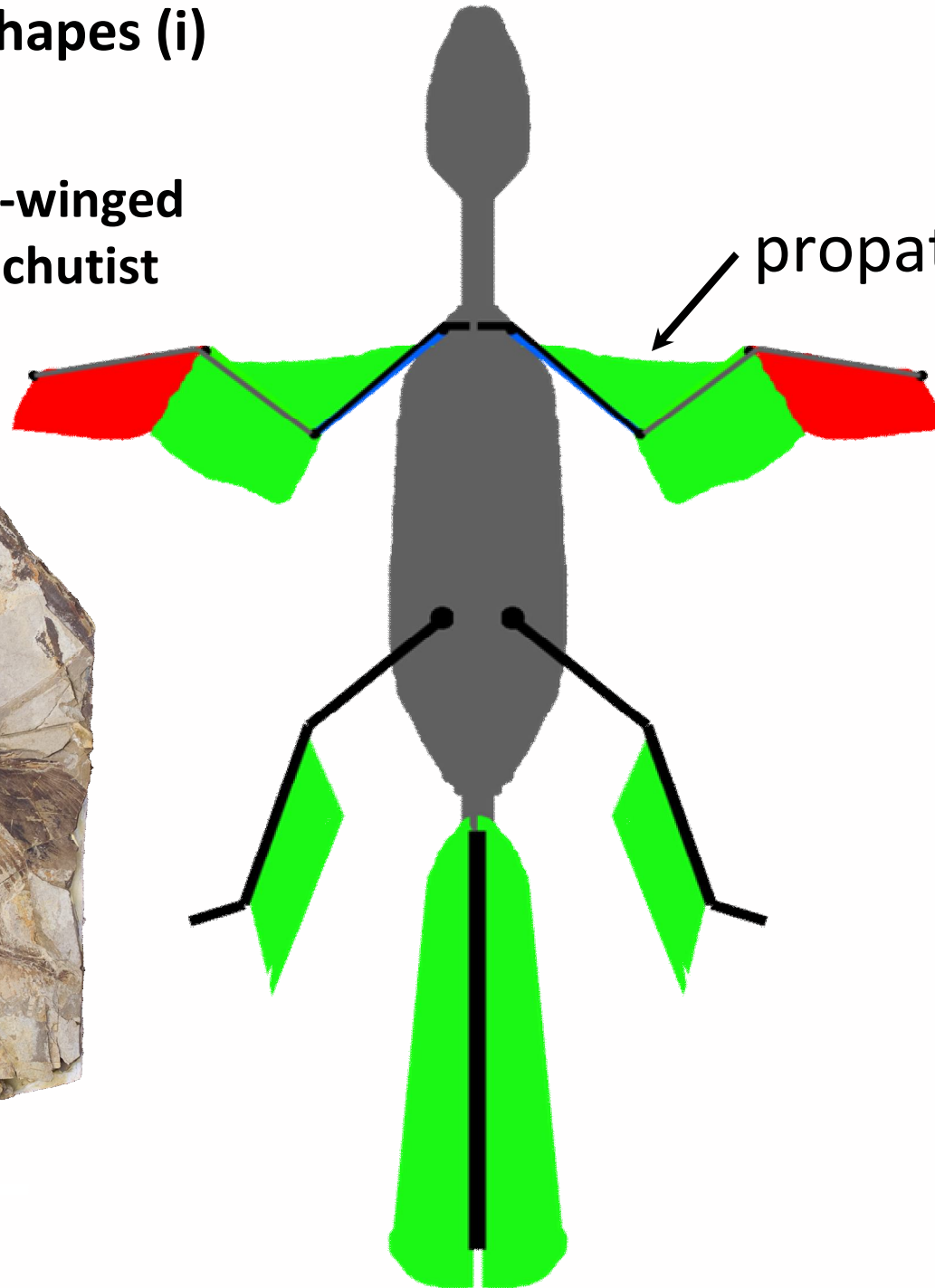




Evolution of wing shapes (i)

Small-winged
parachutist

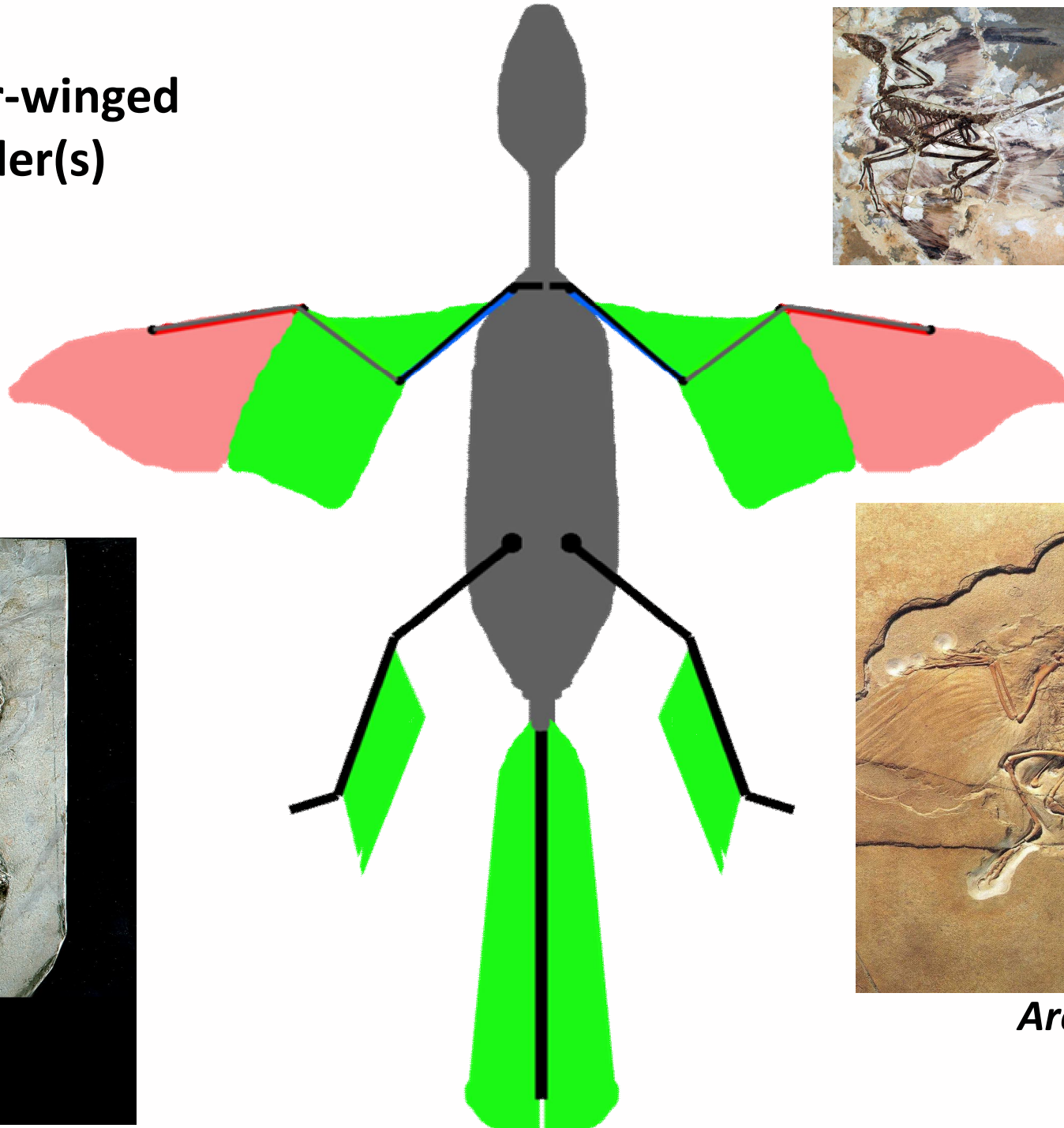
propatagium?



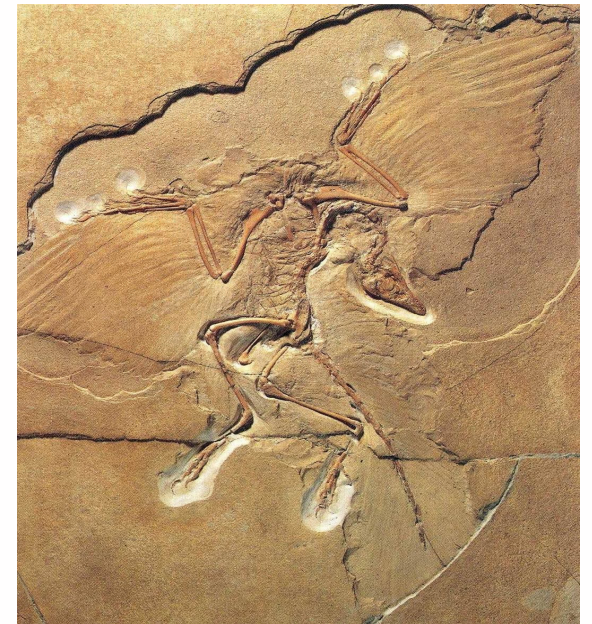
Longer-winged
glider(s)



Microraptor

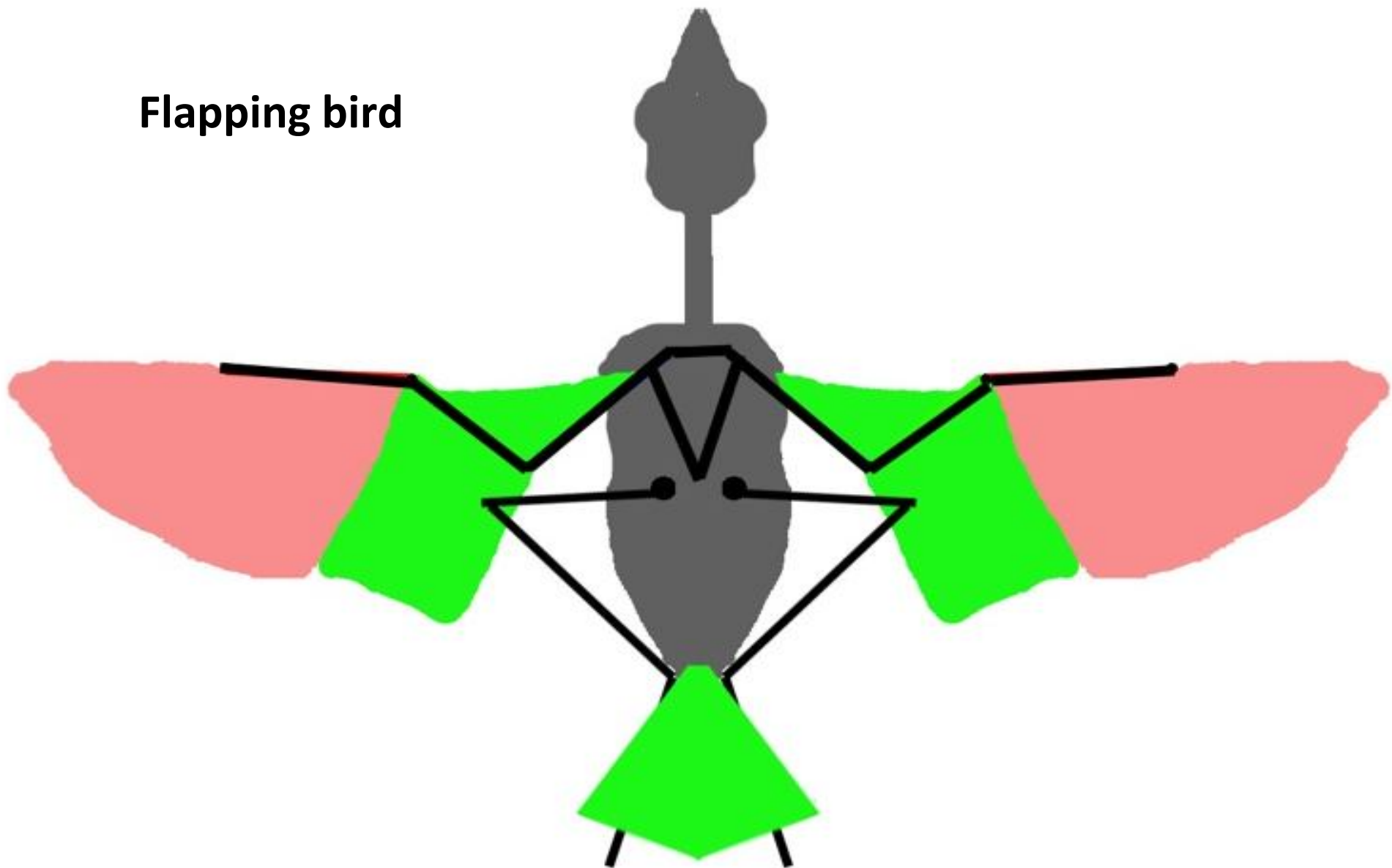


Confuciusornis



Archaeopteryx

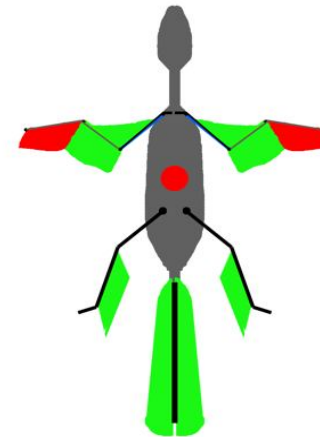
Flapping bird



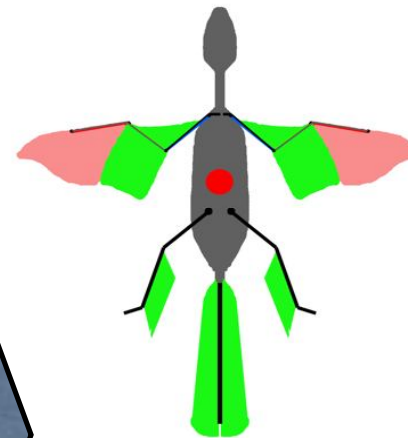
Evolution of wing shapes (ii)



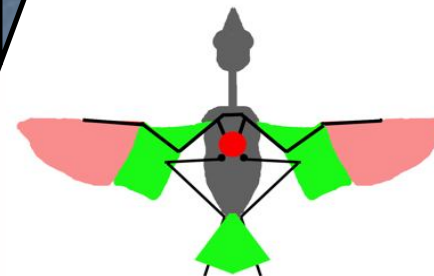
Confuciusornis
Sapeornis



- Phase 1: Parachutist,**
- minimal control
 - lift distributed widely



- Phase 2: Glider,**
- greater lift but still widely distributed
 - perhaps some control from primaries
 - greater wing span (shallower glide angle)

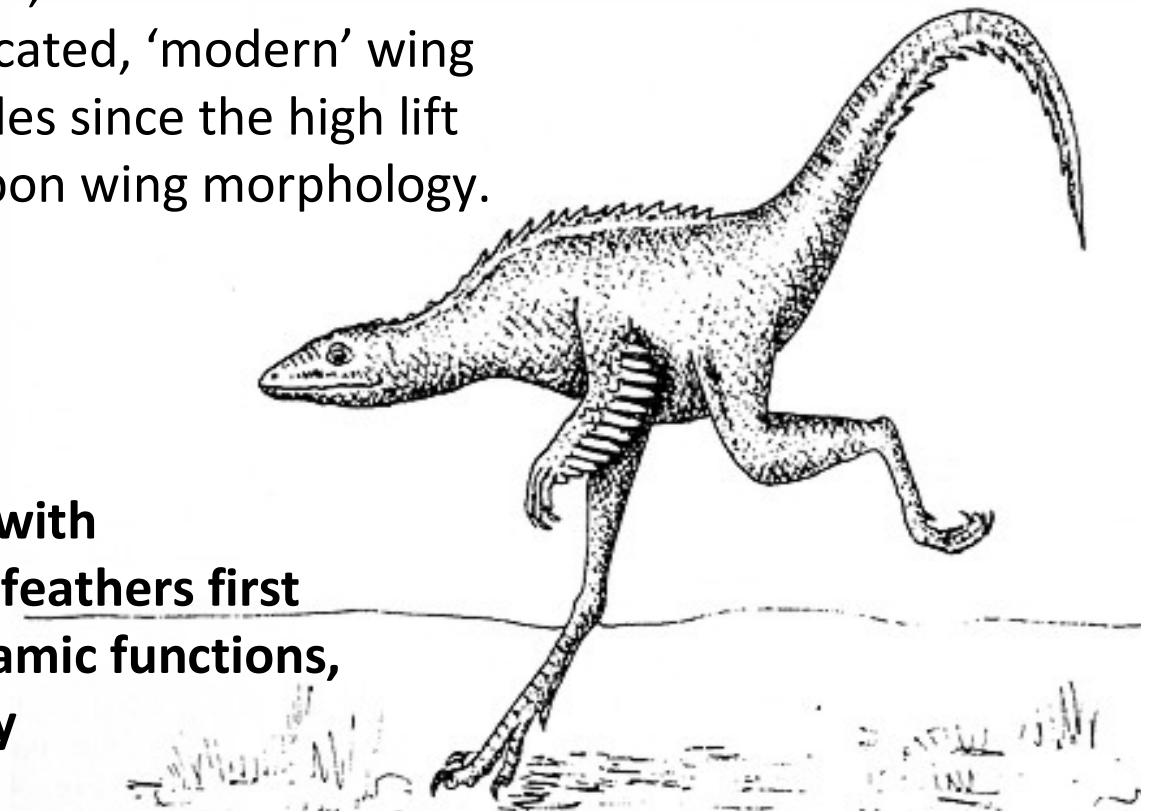


- Phase 3: Flyer.**
- controlling primaries
 - short tail
 - centre shifted forward by greater mass of flight muscles, large brain and eyes

Conclusions

- Microraptor* was most stable when gliding at high lift coefficients and consequently degraded lift/drag ratios;
- This behaviour had adaptive advantages since sustaining a high lift coefficient at the expense of high drag is the most efficient strategy for gliding from, and between, low elevations;
- Anatomically plausible changes in wing configuration and leg position made little difference to aerodynamic performance;
- Microraptor* did not require a sophisticated, 'modern' wing morphology to undertake effective glides since the high lift coefficient regime is less dependent upon wing morphology.

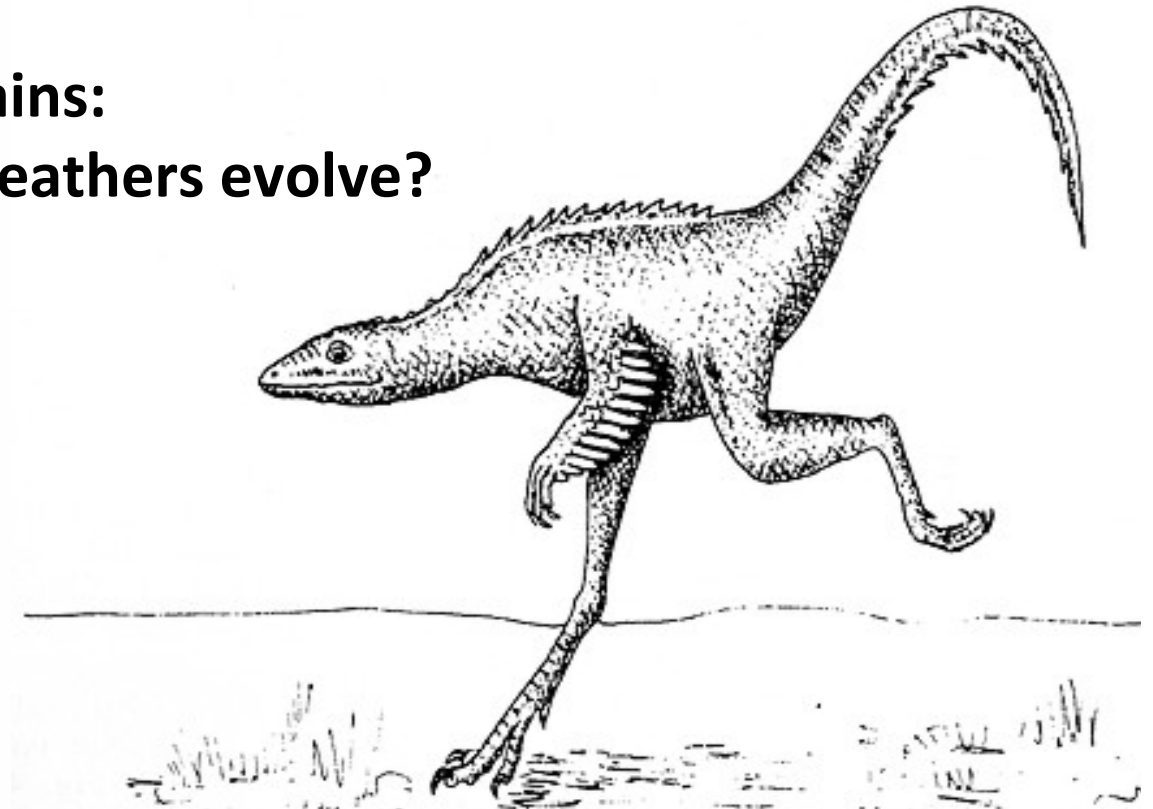
Congruent with the fossil record, and with the hypothesis that symmetric 'flight' feathers first evolved in dinosaurs for non-aerodynamic functions, later adapted to form aerodynamically capable surfaces.



We have also shown

- New fossil evidence for the evolution of wing shape (the primitive condition)
- Hypothetical stages in the evolution of flight surfaces (to be tested by analysis of fossils).

**The question remains:
if not for flight, then why did feathers evolve?**



**If not for flight, then why did feathers evolve?
(one possible mechanism)**



‘the sleeping troodontid’



Mei

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Gary Kaiser



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